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Total Number of Pages : 02

Course: B.Tech  
Sub\_Code: RNM6A002

6<sup>th</sup> Semester Regular/Back Examination: 2022-23

SUBJECT: Numerical Methods

BRANCH(S): CSE, CSEAIME

Time : 3 Hour

Max Marks : 100

Q.Code : M137

Answer Question No.1 (Part-1) which is compulsory, any eight from Part-II and any two from Part-III.

The figures in the right hand margin indicate marks.

Part-I

Q1 Answer the following questions:

(2 x 10)

- What are the order of convergence of Secant and Newton Raphson method?
- Explain the geometrical interpretation of Regula Falsi method.
- Determine L and U to compute the LU factorization of the matrix

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 4 & 5 & 2 \\ 2 & -2 & 0 \end{pmatrix}$$

- Write the sum of  $0.123 \times 10^3$  and  $0.456 \times 10^2$  in 3 digits mantissa form.
- Write the error term in interpolation.
- Write the Newton-Cotes quadrature integration formula?
- If  $f(x) = \frac{1}{x^2}$ , find the divided difference  $f[x_1, x_2, x_3]$ .
- How many nodes should be there for Simpson's  $\frac{1}{3}rd$  rule?
- What do you mean by spectral radius?
- Find  $y(0.2)$  by Euler's method, given that  $\frac{dy}{dx} = x + y$ ;  $y(0) = 1$  with  $h = 0.1$

Part-II

Q2 Only Focused-Short Answer Type Questions- (Answer Any Eight out of Twelve) (6 x 8)

- Find the solution of the below system of equations correct to three decimal places, using the Gauss-Seidel iteration method:

$$45x_1 + 2x_2 + 3x_3 = 58$$

$$-3x_1 + 22x_2 + 2x_3 = 47$$

$$5x_1 + x_2 + 20x_3 = 67$$

- Find a real root of the equation  $\cos x = 3x - 1$  correct to four decimal places by fixed point iteration method.
- Find the smallest positive real root of the  $\tan x + \tanh(x) = 0$  by using Bisection method.
- Define truncation error. What is the absolute, percentage and relative errors involved if  $y = \frac{2}{3}$  is represented in normalized decimal form with 6-digits?

- e) Evaluate  $\int_1^{1.4} e^{-x^2} dx$  dividing the range in to 4 equal parts by Simpson's  $\frac{1}{3}rd$  rule.
- f) Find the missing term in the table using Lagrange's interpolation
- |     |   |   |   |   |    |
|-----|---|---|---|---|----|
| $x$ | 0 | 1 | 2 | 3 | 4  |
| $y$ | 1 | 3 | 9 | — | 81 |
- g) Evaluate  $\int_0^1 \frac{dx}{1+x^2}$  using Trapezoidal rule with  $h=0.2$ . Hence obtain an approximate value of  $\pi$
- h) Derive Newton's divided difference interpolating formula which interpolates a function at  $x = x_i, i = 0, 1, \dots, n$ . Mention its error factor.
- i) Find the value of  $y(0.04)$  using Euler's method, given that  $y' + y = 0, y(0) = 1, h = 0.01$
- j) Find the approximate value of the integral  $\int_0^1 \frac{dx}{1+x}$  using composite trapezoidal rule with 2, 3, 5, 9 nodes and Romberg integration.
- k) Using improved Euler's method find  $y$  at  $x = 0.1$  and  $x = 0.2$ , given  $y' = y - \frac{2x}{y}, y(0) = 1$  with  $h = 0.1$ .
- l) Using fourth order Runge-Kutta method, find  $f(1.4)$  if  $y' = y - x^2 + 1, y(0) = 0.5, h = 0.2$ .

### Part-III

#### Only Long Answer Type Questions (Answer Any Two out of Four)

- Q3** Solve the system of equations  $Ax = b$ , where  $A = \begin{bmatrix} 2 & 1 & 1 & -2 \\ 4 & 0 & 2 & 1 \\ 3 & 2 & 2 & 0 \\ 1 & 3 & 2 & -1 \end{bmatrix}, b = \begin{bmatrix} -10 \\ 8 \\ 7 \\ -5 \end{bmatrix}$ , (16)
- using the LU decomposition method. Take all the diagonal elements of  $L$  as 1. Also find  $A^{-1}$ .
- Q4** Write three properties of Quadratic Spline interpolation. For the data given below (16)
- |        |   |   |    |     |
|--------|---|---|----|-----|
| $x$    | 0 | 1 | 2  | 3   |
| $f(x)$ | 1 | 2 | 33 | 244 |
- fit quadratic splines with  $f''(0) = M(0) = 0$ . Hence, find an estimate of  $f(2.5)$ .
- Q5** Find the general solution of the system of equations (16)
- $$\frac{dx_1}{dt} = -5x_1 + 2x_2 + t, \frac{dx_2}{dt} = -2x_1 - 2x_2 + e^{-t}.$$
- Q6** Find the eigenvalue correct to three decimal places which is nearest to 5 for the (16)
- matrix  $\begin{bmatrix} 4 & 1 & 0 \\ 1 & 4 & 1 \\ 0 & 1 & 4 \end{bmatrix}$  using inverse power method. Obtain the corresponding eigenvector. Take the initial approximate vector as  $v^{(0)} = [1, 1, 1]^T$ .